

Structure Learning in Undirected Graphical Models

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January 20, 2011

Outline

- 1 Motivation, Classical Methods
- 2 Gaussian and Ising graphical models: ℓ_1 -Regularization
- 3 General pairwise models: Group ℓ_1 -Regularization
- 4 High-order models: Structured Sparsity
- 5 Further Extensions

Motivation for Graphical Model Structure Learning

car	drive	files	hockey	mac	league	pc	win
0	0	1	0	1	0	1	0
0	0	0	1	0	1	0	1
1	1	0	0	0	0	0	0
0	1	1	0	1	0	0	0
0	0	1	0	0	0	1	1

- What words are related?
- Is a post with (car,drive,hockey,pc,win) spam?
- What is $p(\text{car}|\text{drive})$? What about $p(\text{car}|\text{drive},\text{files})$?
- Can we 'fill in' some variables given the others?
- Can we generate more items that look like this?

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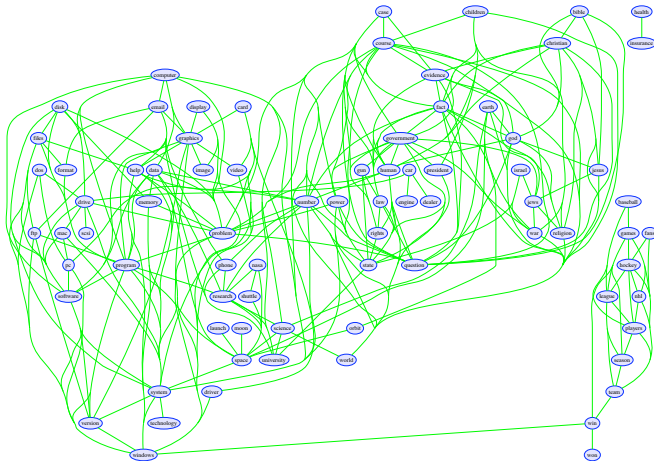
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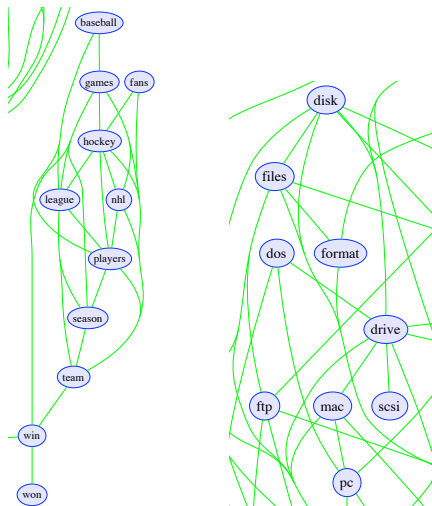
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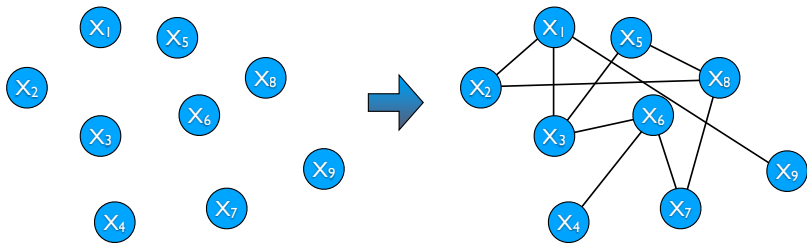
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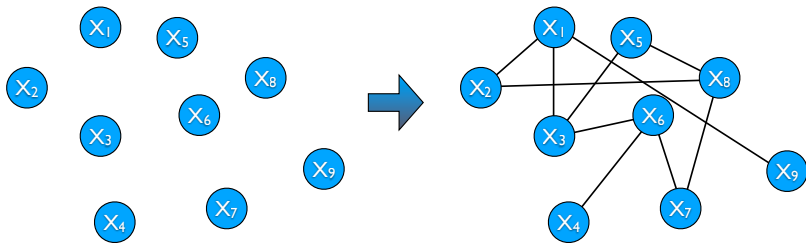


Estimation in Graphical Models with Unknown Structure



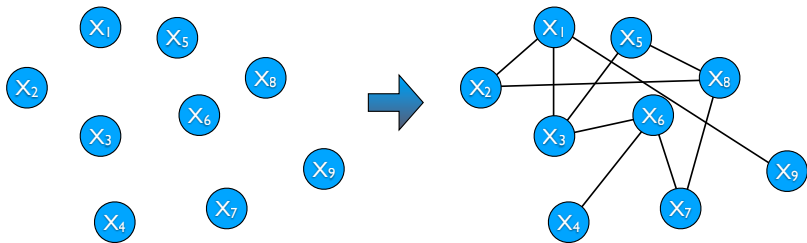
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- Often the graph structure is known (or assumed).
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Motivations for doing Structure Learning

- One approach to this task is to simply fit a **dense** model.
- Alternately, we can search for a sparse set of edges.
- Reasons why we might prefer the sparse approach:
 - Statistical efficiency
 - Computational efficiency
 - Structural discovery
- There are two classical methods for estimating sparse models:
 - Constraint-based approaches
 - Search and score approaches

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Constraint-based Methods 1: Marginal Independence

- Perform a series of (in)dependence tests to discover the edges.
- One approach is using a pairwise (in)dependence statistic to:
 - Select the 'top-k' neighbors.
 - Select those above a threshold.
- Assesses **marginal** instead of conditional dependence:
 - 'true' neighbors may not have highest marginal dependence.
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Constraint-based Methods 2: Conditional Independence

- More advanced methods use **conditional independence tests**.
[Verman & Pearl, 1990, Spirtes and Glymour, 1991]
- In some cases, these methods **recover the true structure**.
- However, there are several practical drawbacks:
 - Number and size of possible conditioning sets is **exponential**.
 - Multiple testing gives **low statistical power**.
 - Potential for **propagation of errors**.
 - Tests **don't assess ability of structure to model the data**.
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Search and Score 1: Greedy Forward/Backward

- Classical search and score methods:

- Start with the empty structure
- Add the edge that improves the likelihood the most.
- Test for sufficient improvement in the likelihood.
- Stop when the test fails.

[Dempster, 1972, Goodman, 1971]

(you can also start with the full structure and work backwards)

- Very expensive in high dimensions:

- Fits $\mathcal{O}(p^2)$ models at each of $\mathcal{O}(p^2)$ steps.
- In Gaussian graphical models, fitting model require $\mathcal{O}(p^3)$.

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 - Define a score on structure and parameters.
 - Use combinatorial-search techniques to optimize the score.
 - Consider a restricted class of models (chordal, low treewidth).
 - Use heuristics to approximately evaluate $\mathcal{O}(p^2)$ candidates.
- But these methods still have drawbacks:
 - The search space is enormous, $2^{p(p-1)/2}$ possible models.
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Motivation for NOT doing Structure Learning

- Recall the reasons we wanted to do structure learning:
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 - Structural discovery
- But, even greedy search methods are **extremely expensive**.
- A high-dimensional alternative is fit single dense model but:
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Graphical Model Structure Learning with ℓ_1 -Regularization

- We focus on an intermediate between fitting a dense and sparse model:
 - Fit a single dense model (possibly with approximations).
 - Use ℓ_1 -regularization to encourage parameter sparsity.
- We parameterize the model so that parameter sparsity is equivalent to graph sparsity.
- Estimates a sparse model by fitting a single dense model.

Summary of Contributions

- There has been growing interest in this approach:
 - Gives **regularized** estimate (like ℓ_2 -regularization).
 - Gives **sparse** estimate (like search methods).
 - Formulated as a **convex** optimization.
- But previous work usually makes two unrealistic assumptions:
 - Parameters and edges have a **one-to-one correspondence**.
 - The model only includes **pairwise dependencies**.
- This talk outlines methods that remove these assumptions.

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Pairwise Undirected Graphical Models (UGMs)

- Pairwise UGMs represent multivariate distributions as a normalized product of non-negative potential functions:

$$p(x_1, x_2, \dots, x_p) = \frac{1}{Z} \prod_{i=1}^p \phi_i(x_i) \prod_{(i,j) \in E} \phi_{ij}(x_i, x_j)$$

- Z is the constant that makes the distribution integrate to one.
- Models the pairwise statistics of all pairs of variables in E .

Continuous Structure Learning in UGMs

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- Structure learning is the task of choosing the edge set E .
- Removing the edge is the same as setting $\phi_{ij}(x_i, x_j) = 1, \forall ij$.
- We parameterize so that zero parameters make $\phi_{ij}(x_i, x_j) = 1$.
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Optimization with ℓ_1 -Regularization

- Various fields are now interested in ℓ_1 -regularization:

$$\min_{\mathbf{w}} f(\mathbf{w}) + \sum_{i=1}^p \lambda_i |w_i|$$

- There are efficient algorithms for solving this type of problem.
- Under suitable assumptions, yields a sparse solution:
 - Many coefficients w_i are exactly zero.

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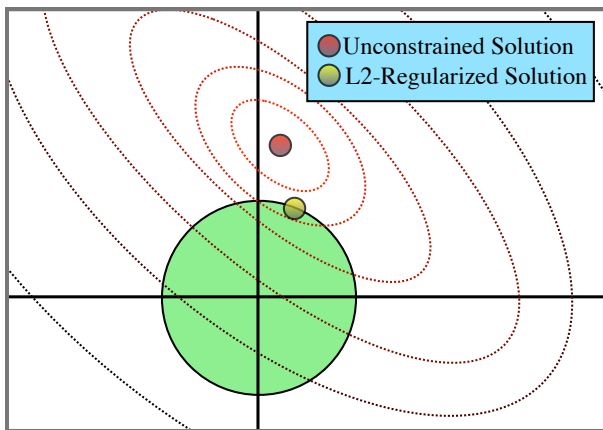
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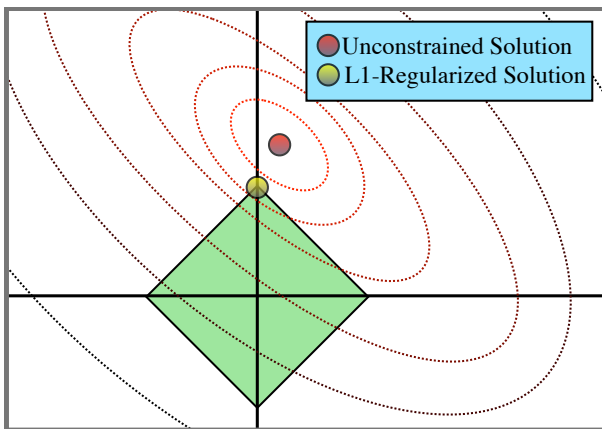
ℓ_2 -Regularization vs. ℓ_1 -Regularization

ℓ_2 -regularization is equivalent to optimization over an ℓ_2 -norm ball:



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Continuous Variables: Gaussian Graphical Models (GGMs)

- Structure learning with ℓ_1 -regularization was first explored for **Gaussian graphical models** (GGMs).
- GGMs model a multivariate distribution over continuous variables as a multivariate Gaussian distribution:

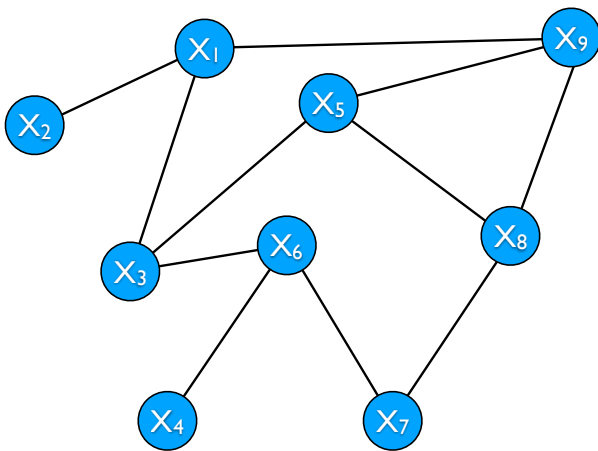
$$p(x_1, x_2, \dots, x_p) = \frac{1}{Z} \exp\left(-\frac{1}{2}(\mathbf{x} - \mathbf{b})^T W(\mathbf{x} - \mathbf{b})\right)$$

- The normalizing constant Z is

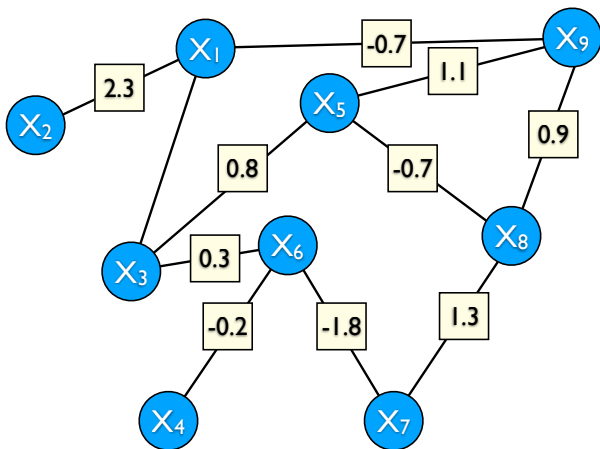
$$Z = (2\pi)^{p/2} |W|^{-1/2}$$

- Edges correspond to non-zero elements of the **precision** W .

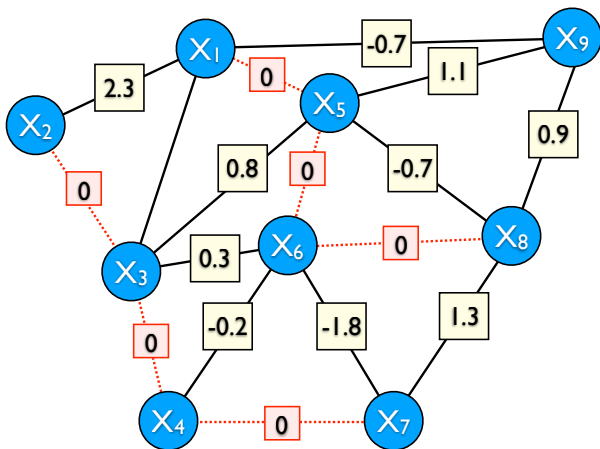
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- GGM structure learning with ℓ_1 -regularization of the precision:

$$\min_{W \succ \mathbf{0}, \mathbf{b}} - \sum_{m=1}^n \log p(\mathbf{x}^m | W, \mathbf{b}) + \sum_{i=1}^p \sum_{j=1}^p \lambda_{ij} |W_{ij}|$$

- First explored in [Dahl et al., 2005, Banerjee et al., 2006, Meinshausen & Buhlmann, 2006, Yuan and Lin, 2007].
- Sometimes called the **graphical LASSO**.
- Convex optimization is easily solved with 1000s of variables.

Binary Variables: Ising Graphical Models (IGMs)

- This idea was next explored for Ising graphical models:

$$p(x_1, x_2, \dots, x_p) = \frac{1}{Z} \exp\left(\sum_{i=1}^p x_i b_i + \sum_{(i,j) \in E} x_i x_j W_{ij}\right)$$

- The normalizing constant Z is

$$Z = \sum_{\mathbf{x}'} \exp\left(\sum_{i=1}^p x'_i b_i + \sum_{(i,j) \in E} x'_i x'_j W_{ij}\right)$$

- Setting the edge weight W_{ij} to zero removes the edge.
- IGM structure learning with ℓ_1 -regularization:

$$\min_{W, \mathbf{b}} - \sum_{m=1}^n \log p(\mathbf{x}^m | W, \mathbf{b}) + \sum_{i=1}^p \sum_{j=1}^p \lambda_{ij} |W_{ij}|$$

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Approximations for IGMs

- IGM case is more difficult than GGM case because of Z :
 - Z can be computed in $\mathcal{O}(p^3)$ for GGMs
 - In general, it is $\#P$ -hard to evaluate Z in IGMs.
- Several ways to address this have been explored:
 - Asymmetric pseudo-likelihood [Wainwright et al., 2006].
 - Bethe approximation [Lee et al., 2006].
 - Symmetric pseudo-likelihood [Schmidt et al., 2008].
 - Mean-field approximation, convex Bethe approximation.
 - Logdet approximation [Banerjee et al., 2008].
 - Cutting-plane refinement [Kolar and Xing, 2008].

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Structure Learning with Group ℓ_1 -Regularization

- In GGMs/IGMs, there is a **one-to-one** correspondence between parameters and edges.
- In some case, we want sparsity in **groups** of parameters:
 - General log-linear models [Lee et al., 2006].
 - Blockwise-sparse models [Duchi et al., 2008].
 - Conditional random fields [Schmidt et al., 2008].
- In these cases, we can use **group ℓ_1 -regularization**.

General Pairwise Log-Linear Models

- In **log-linear models**, the log-potentials are linear functions.
- IGMs are a special case with binary variables.

$$\log \phi_{ij}(x_i, x_j, w_{ij}) = x_i x_j w_{ij}$$

- But log-linear models allow non-binary discrete variables.
- Also useful for (discretized) non-Gaussian continuous data.
- The potentials for an edge between three-state variables:

$$\log \phi_{ij}(\cdot, \cdot, \mathbf{w}_{ij}) = \begin{bmatrix} w_{ij11} & w_{ij12} & w_{ij13} \\ w_{ij21} & w_{ij22} & w_{ij23} \\ w_{ij31} & w_{ij32} & w_{ij33} \end{bmatrix}$$

- We must set all 9 elements to zero to remove the edge.

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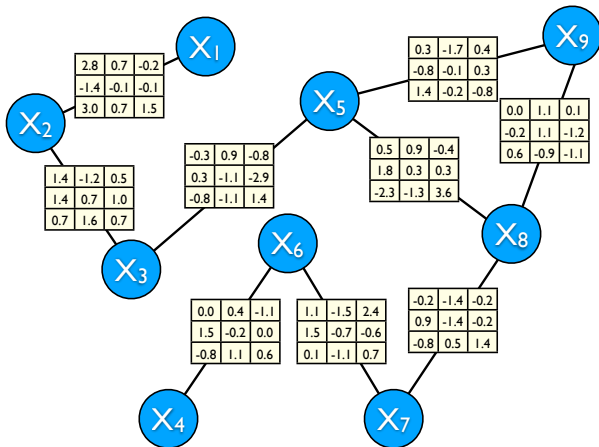
$$\log \phi_{ij}(x_i, x_j, w_{ij}) = x_i x_j w_{ij}$$

- But log-linear models allow non-binary discrete variables.
- Also useful for (discretized) non-Gaussian continuous data.
- The potentials for an edge between three-state variables:

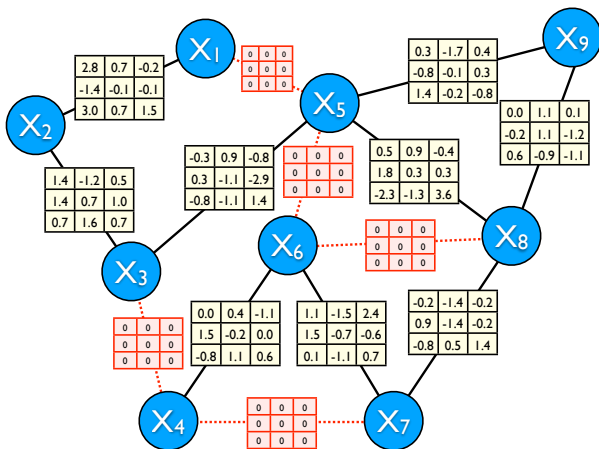
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- We must **set all 9 elements to zero** to remove the edge.

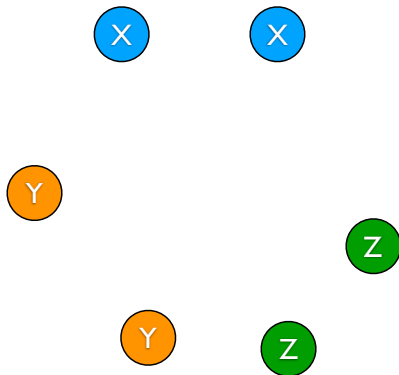
General Pairwise Log-Linear Models



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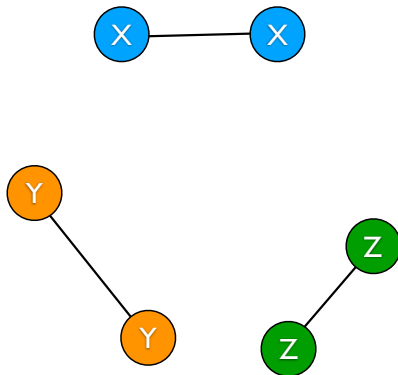


Blockwise Sparsity



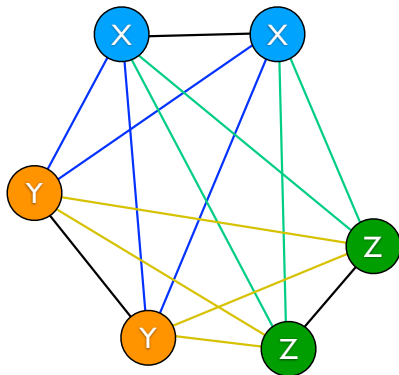
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- We expect some types to be conditionally independent.

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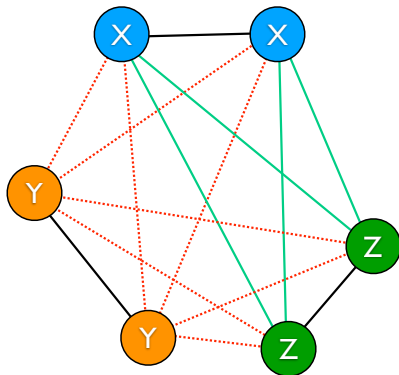
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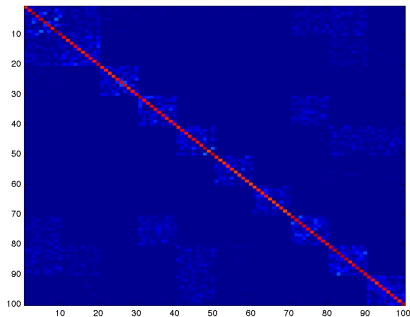
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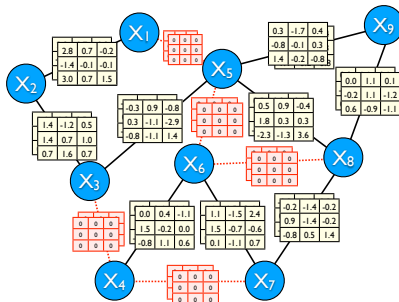
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Blockwise Sparsity



- In GGMs/IGMs, corresponds to **blockwise-sparsity** in matrix.

Conditional Random Fields



- In some scenarios, we also have **covariates**.
- We can consider doing **conditional structure learning**.
- Here, we have a tensor of variables associated with each edge.

Group ℓ_1 -Regularization

- In all these cases, we want **sparsity in groups** of parameters.
- This can be accomplished with **group ℓ_1 -regularization**:

$$\min_{\mathbf{w}} f(\mathbf{w}) + \sum_g \lambda_g \|\mathbf{w}_g\|_2$$

- Applies **ℓ_1 -regularization to the lengths of the groups**.
- An alternative is group ℓ_1 -regularization with the ℓ_∞ -norm:

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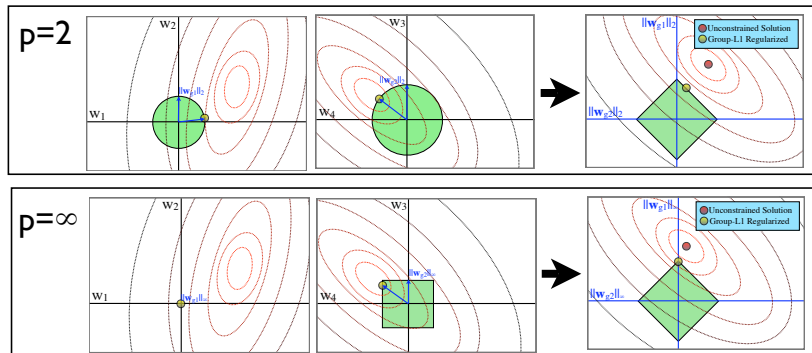
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Group ℓ_1 -Regularization



Group ℓ_1 -Regularization with Matrix Groups

- In several of the examples, the groups form **matrices**.
- For matrix groups, an alternative is the nuclear norm:

$$\min_{\mathbf{W}_1, \mathbf{W}_2, \dots, \mathbf{W}_G} f(\mathbf{W}_1, \mathbf{W}_2, \dots, \mathbf{W}_G) + \sum_g \lambda_g \|\mathbf{W}_g\|_\sigma$$

- The nuclear norm, $\|\mathbf{W}_g\|_\sigma$, is the **sum of singular values**.
- Applies ℓ_1 -regularization to the singular values of the groups.
- Encourages the matrices to be low-rank.

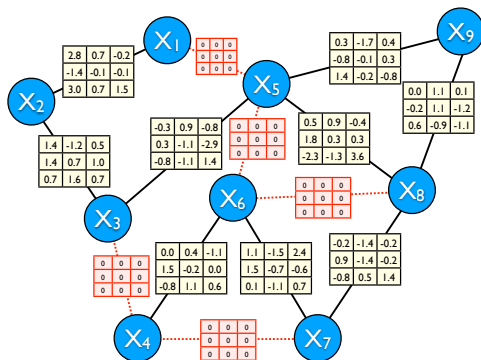
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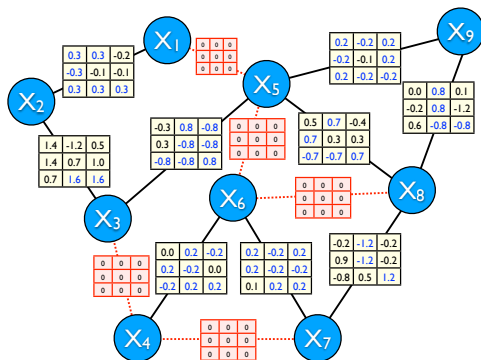
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Structure Learning with Group ℓ_1 -Regularization



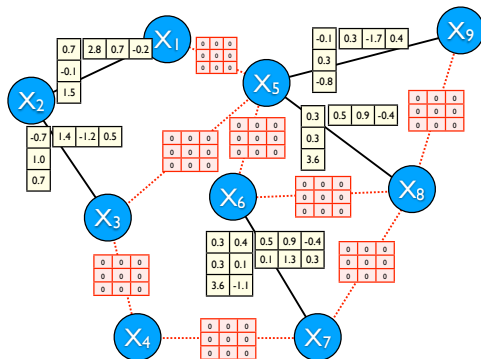
- Group ℓ_1 -Regularization with the ℓ_2 group norm.
- Encourage **group** sparsity.

Structure Learning with Group ℓ_1 -Regularization



- Group ℓ_1 -Regularization with the ℓ_∞ group norm.
- Encourage **group** sparsity and **parameter tying**.

Structure Learning with Group ℓ_1 -Regularization



- Group ℓ_1 -Regularization with the nuclear group norm.
- Encourage group sparsity and low-rank.

Experiments Comparing Parameterizations and Norms

- We tested three log-linear edge parameterizations:

$$\log \phi_{ij}(\cdot, \cdot, w_{ij}) = \begin{bmatrix} w_{ij} & 0 & 0 \\ 0 & w_{ij} & 0 \\ 0 & 0 & w_{ij} \end{bmatrix} \quad (\text{Ising potentials})$$

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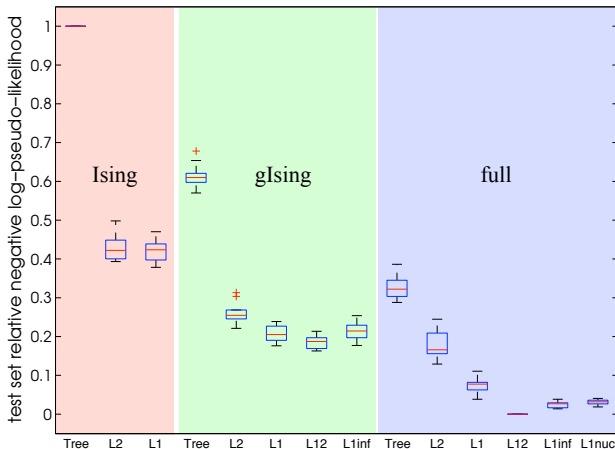
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Experiments Comparing Parameterizations and Norms

- We also tested six regularization strategies:
 - **Tree**: Maximum-likelihood tree structure.
 - **L2**: ℓ_2 -Regularization (squared).
 - **L1**: ℓ_1 -Regularization.
 - **L12**: Group ℓ_1 -Regularization (ℓ_2 -norm).
 - **L1inf**: Group ℓ_1 -Regularization (ℓ_∞ -norm).
 - **L1nuc**: Group ℓ_1 -Regularization (nuclear norm).

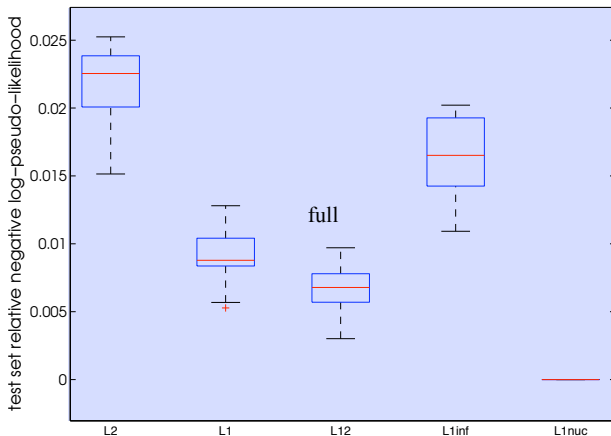
Experimental Comparison of Different Norms

Results on heart wall motion abnormality data (16 nodes, 5 states):



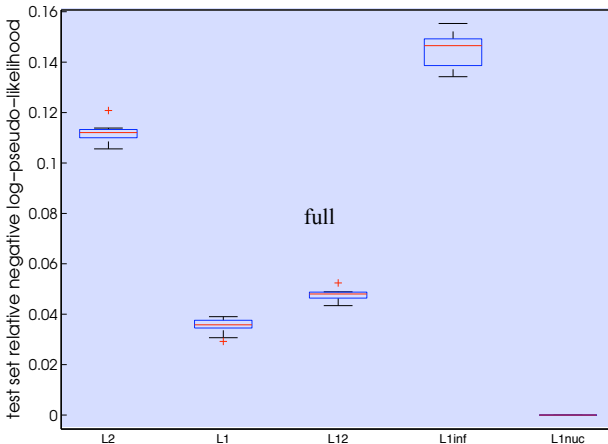
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Results on USPS digits data (256 nodes, 4 discretization levels):



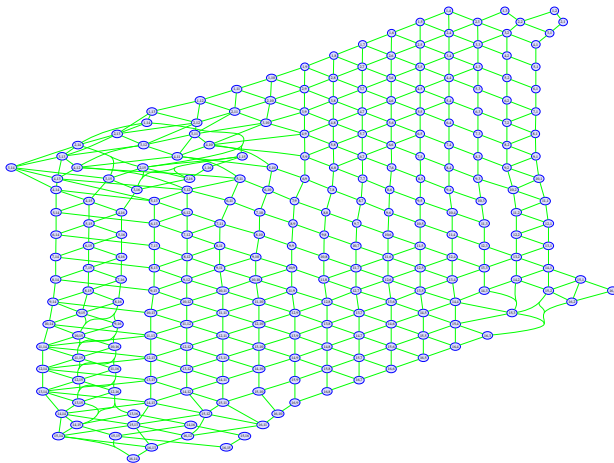
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Results on USPS digits data (256 nodes, 8 discretization levels):



Experimental Comparison of Different Norms

Estimated structure on USPS data:



Outline

- 1 Motivation, Classical Methods
- 2 Gaussian and Ising graphical models: ℓ_1 -Regularization
- 3 General pairwise models: Group ℓ_1 -Regularization
- 4 High-order models: **Structured Sparsity**
 - Hierarchical Log-Linear Models
 - Active Set Method
 - Experiments
- 5 Further Extensions

Structure Learning with ℓ_1 -Regularization

A list of papers on this topic (incomplete):

[Li & Yang, 2004], [Li & Yang, 2005], [Banerjee et al., 2006], [Huang et al., 2006], [Lee et al., 2006], [Meinshausen & Bühlmann, 2006], [Wainwright et al., 2006], [Dahinden et al., 2007], [Schmidt et al., 2007], [Shimamura et al., 2007], [Yuan & Lin, 2007], [d'Aspremont et al., 2008], [Banerjee et al., 2008], [Dahl et al., 2008], [Duchi et al., 2008], [Friedman et al., 2008], [Kolar & Xing, 2008], [Levina et al., 2008], [Schmidt et al., 2008], [Fan & Feng, 2009], [Höling & Tibshirani, 2009], [Krishnamurphy & d'Aspremont, 2009], [Lu, 2009a], [Lu, 2009b], [Marlin et al., 2009a], [Marlin et al., 2009b], [Schmidt et al., 2009], [Schmidt & Murphy, 2009], [Schnitzspan et al., 2009], [Yuan, 2009], [Vidaurre et al., 2010].

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Beyond Pairwise Potentials

- The pairwise assumption is inherent to Gaussian models.
- The pairwise assumption has not traditionally been associated with log-linear models [Goodman, 1971], [Bishop et al., 1975].
- The assumption is restrictive if higher-order statistics matter.
- Eg. Mutations in both gene A and gene B lead to cancer.
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In log-linear models [Bishop et al., 1975] we write the probability of a vector $\mathbf{x} \in \{1, 2, \dots, k\}^p$ as a normalized product

$$p(\mathbf{x}) \triangleq \frac{1}{Z} \prod_{A \subseteq S} \phi_A(\mathbf{x}_A),$$

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The full parameterization for a threeway potential on binary nodes,

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If $\mathbf{w}_A = \mathbf{0}$ and $A \subset B$, then $\mathbf{w}_B = \mathbf{0}$.

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Bach [2008], Zhao et al. [2009] enforce hierarchical inclusion restrictions with **overlapping** group ℓ_1 -regularization. (also known as **structured sparsity**)

Example:

- We can enforce that B is zero whenever A is zero by using two groups: $\{B\}$ and $\{A, B\}$.
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Active, Inactive, Boundary Groups

- We call A an **active group** if A or some superset of A is non-zero.
- If A is not active, and some subset of A is zero, we call A an **inactive group**.
- The remaining groups are called **boundary group**.
- Boundary groups can be made non-zero without violating hierarchical inclusion.

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Similar to Bach [2008], we use an active set method:

- Find the active groups, and sub-optimal boundary groups.
- Solve the problem with respect to these variables.

This adds groups that satisfy hierarchical inclusion, and where the model poorly estimates the higher-moment in the data.

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Example of Active Set Method

Initial boundary groups.

1

2

3

4

5

1,2

1,3

1,4

1,5

2,3

2,4

2,5

3,4

3,5

4,5

1,2,3

1,2,4

1,2,5

1,3,4

1,3,5

1,4,5

2,3,4

2,3,5

2,4,5

3,4,5

1,2,3,4

1,2,3,5

1,2,4,5

1,3,4,5

2,3,4,5

1,2,3,4,5

Example of Active Set Method

Optimize initial boundary groups.

1

2

3

4

5

1,2

1,3

1,4

1,5

2,3

2,4

2,5

3,4

3,5

4,5

1,2,3

1,2,4

1,2,5

1,3,4

1,3,5

1,4,5

2,3,4

2,3,5

2,4,5

3,4,5

1,2,3,4

1,2,3,5

1,2,4,5

1,3,4,5

2,3,4,5

1,2,3,4,5

Example of Active Set Method

Find new **active groups**.

1

2

3

4

5

1,2

1,3

1,4

1,5

2,3

2,4

2,5

3,4

3,5

4,5

1,2,3

1,2,4

1,2,5

1,3,4

1,3,5

1,4,5

2,3,4

2,3,5

2,4,5

3,4,5

1,2,3,4

1,2,3,5

1,2,4,5

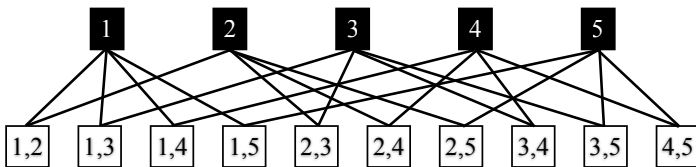
1,3,4,5

2,3,4,5

1,2,3,4,5

Example of Active Set Method

Find new boundary groups.



1,2,3 1,2,4 1,2,5 1,3,4 1,3,5 1,4,5 2,3,4 2,3,5 2,4,5 3,4,5

1,2,3,4

1,2,3,5

1,2,4,5

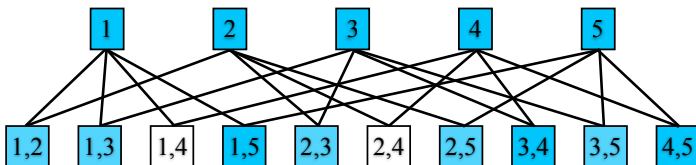
1,3,4,5

2,3,4,5

1,2,3,4,5

Example of Active Set Method

Optimize active groups and sub-optimal boundary groups.



1,2,3 1,2,4 1,2,5 1,3,4 1,3,5 1,4,5 2,3,4 2,3,5 2,4,5 3,4,5

1,2,3,4

1,2,3,5

1,2,4,5

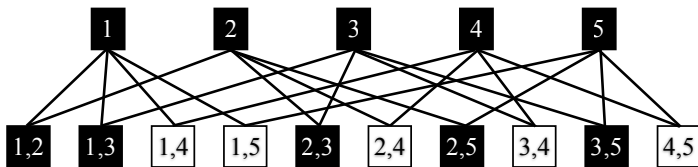
1,3,4,5

2,3,4,5

1,2,3,4,5

Example of Active Set Method

Find new **active groups**.



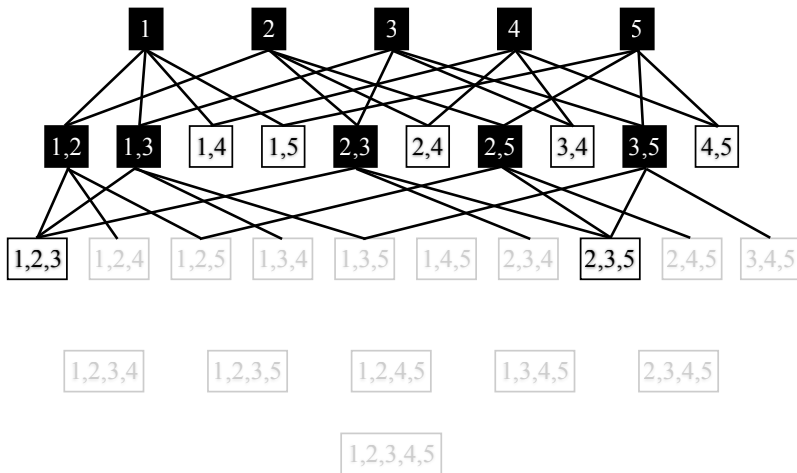
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1,2,3,4,5

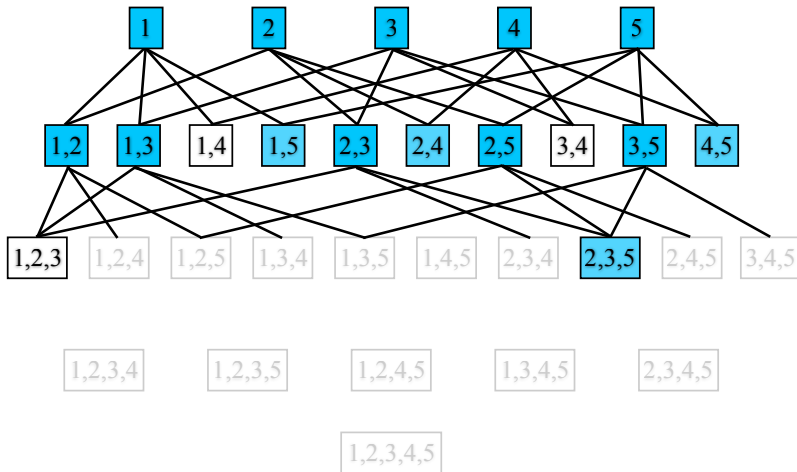
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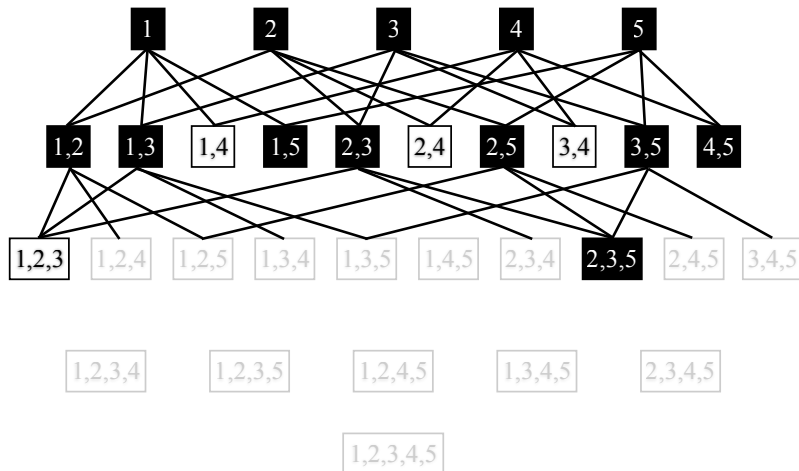
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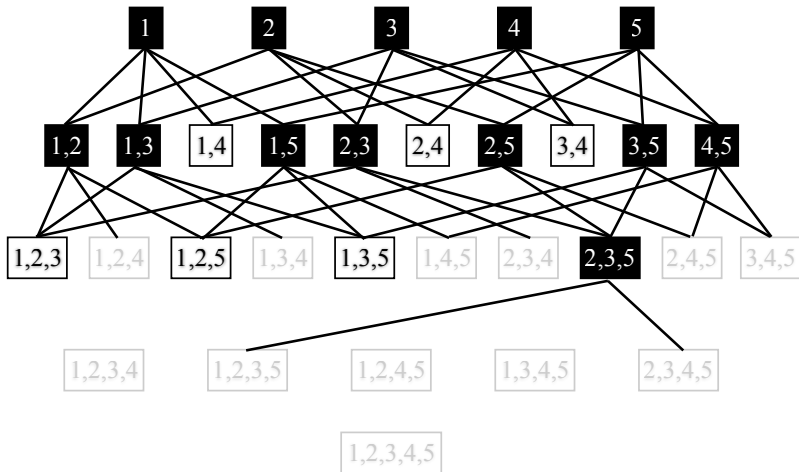
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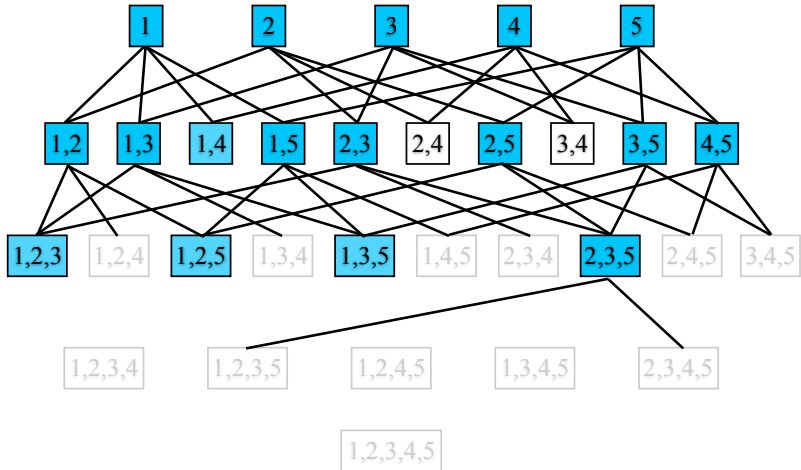
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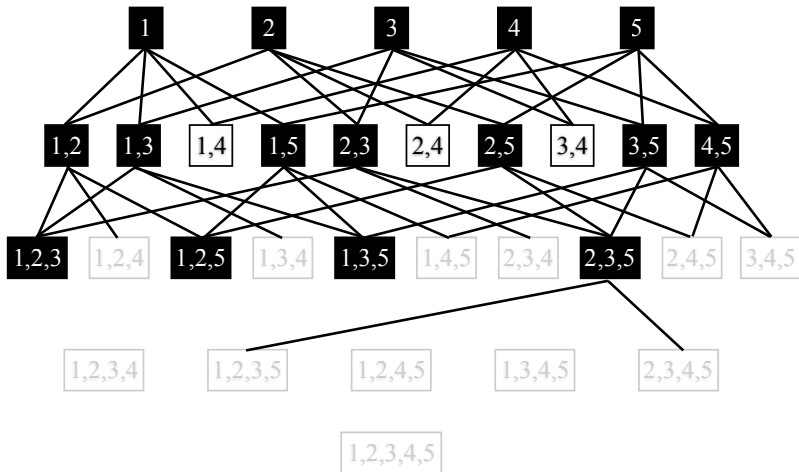
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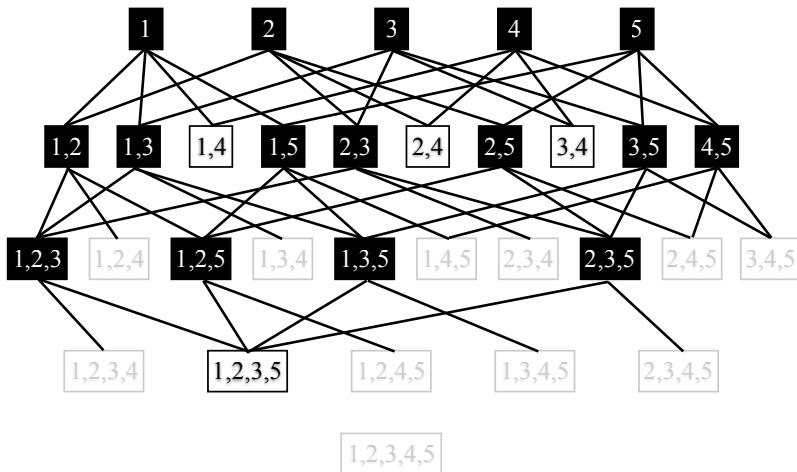
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Find new **active groups**.



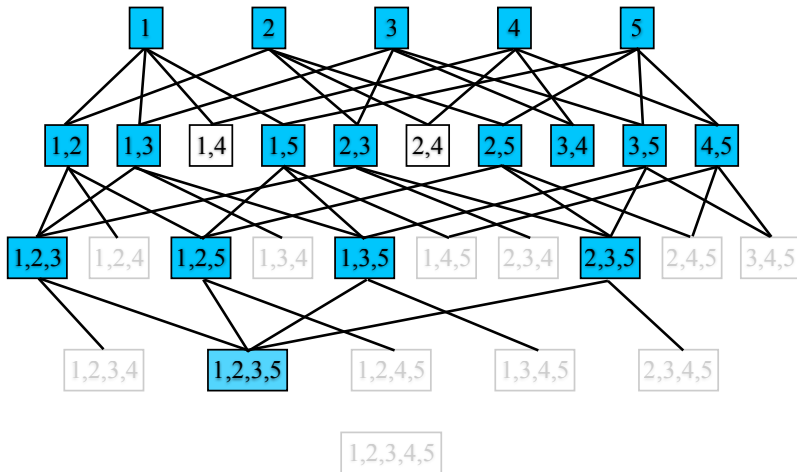
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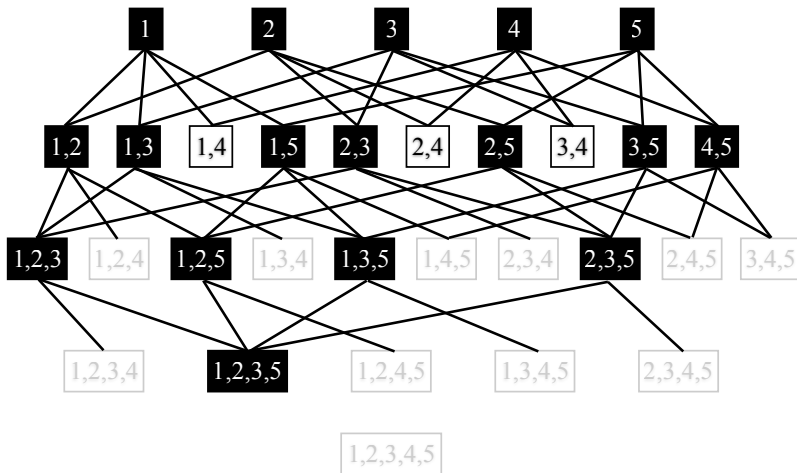
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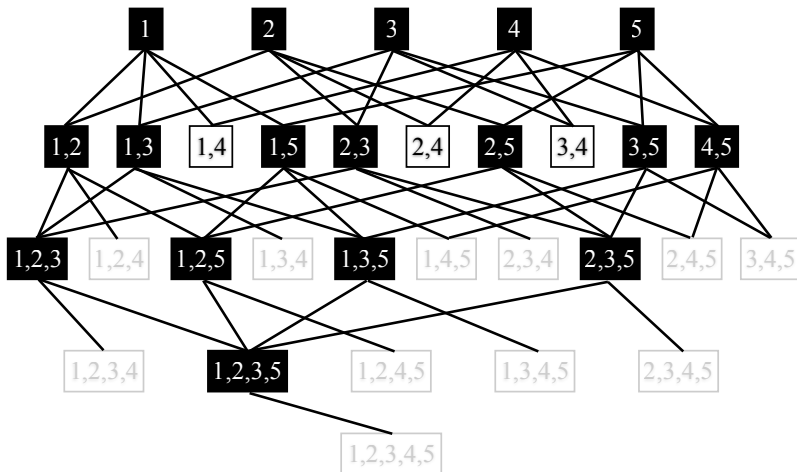
Example of Active Set Method

Find new **active groups**.



Example of Active Set Method

No new boundary groups, so we are done.



Example of Active Set Method

- We only considered 4 of 10 possible threeway interactions, 1 of 5 fourway interactions, and no fiveway interactions.
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Multivariate Flow Cytometry Experiments

Does it empirically help to have higher-order potentials?

We first consider a small data set where we can tractably compute the normalizing constant:

- Multivariate flow cytometry [Sachs et al., 2005].

We compared:

- Pairwise with ℓ_2 -regularization and group ℓ_1 -regularization.
- Threeway with ℓ_2 -regularization and group ℓ_1 -regularization.
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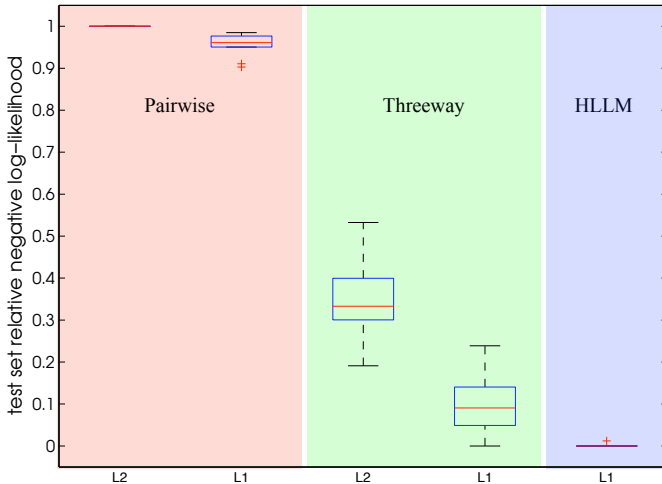
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Flow Cytometry Data



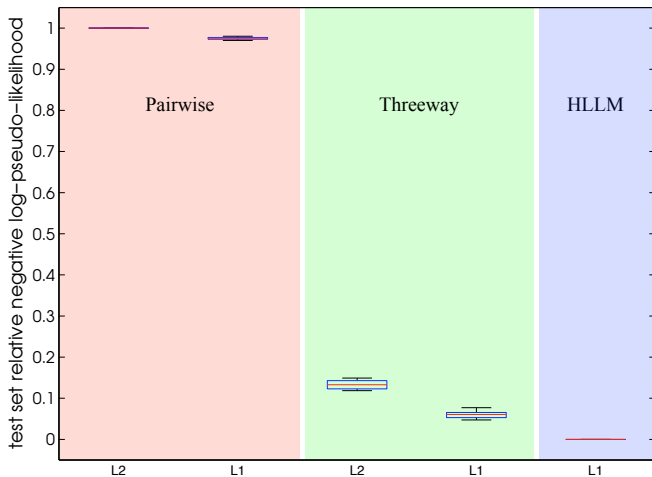
Traffic and USPS Experiments

We next consider two larger data sets:

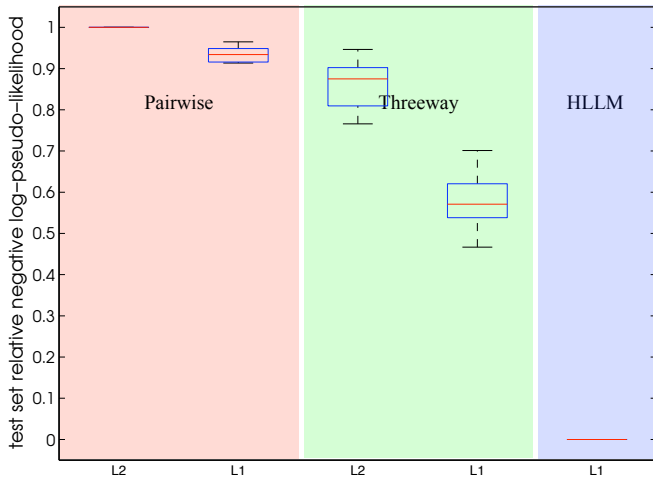
- USPS digits data discretized into four states.
- Traffic flow level [Shahaf et al., 2009].

On these experiments we used glsing potentials, and used a pseudo-likelihood for training/test.

USPS Data



Traffic Flow Data



Structure Estimation

- We sought to test whether the HLLM model could recover a true structure.
- We generated samples from a 10-node data set with potentials $(2,3)(4,5,6)(7,8,9,10)$ and parameters from $\mathcal{N}(0,1)$.
- We recorded the number of false positives of different orders for the first model along the regularization path that includes the true model.
- Eg., with 20000 samples the order was
 $(8,10)(7,9)(9,10)(7,10)(4,5)(8,9)(2,3)(4,6)(8,9,10)(7,8)$
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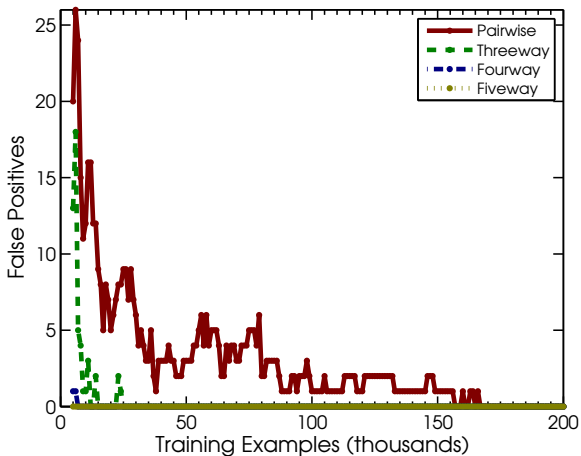
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Synthetic Data: Types of Errors

Types of errors made by HLLM:

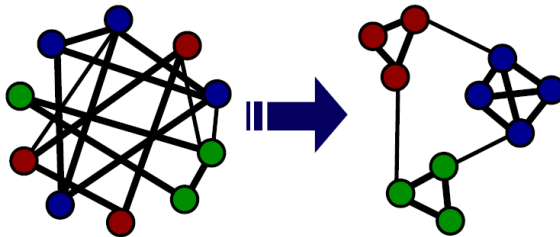


Outline

- 1 Motivation, Classical Methods
- 2 Gaussian and Ising graphical models: ℓ_1 -Regularization
- 3 General pairwise models: Group ℓ_1 -Regularization
- 4 High-order models: Structured Sparsity
- 5 Further Extensions
 - Extensions
 - Summary

Group Sparse Priors for Covariance Estimation

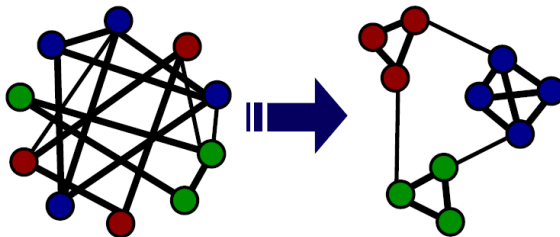
- Earlier we discussed **blockwise-sparse** models.



- What if the blocks aren't completely sparse?
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- We give bounds on integrals of priors over positive-definite matrices, and a variational method that learns the types.
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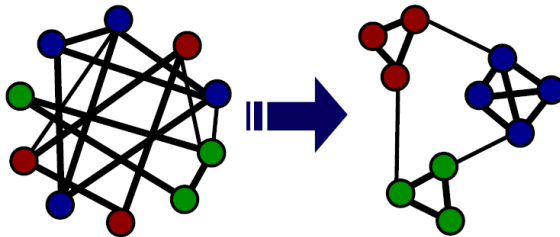
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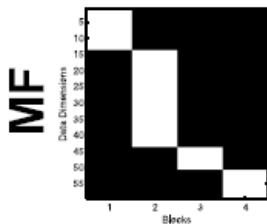
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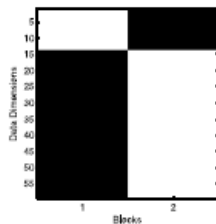
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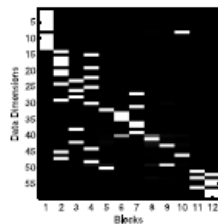
Learned variable types on mutual fund data:
[Scott & Carvalho, 2008]



Known



GL12



GL1

The methods discover the 'stocks' and 'bonds' groups.

Causality: Modeling Interventions

- The difference between **conditioning by observation** and **conditioning by intervention** in the 'hungry at work' problem:
 - If I see that my watch says 11:55, then it's almost lunch time
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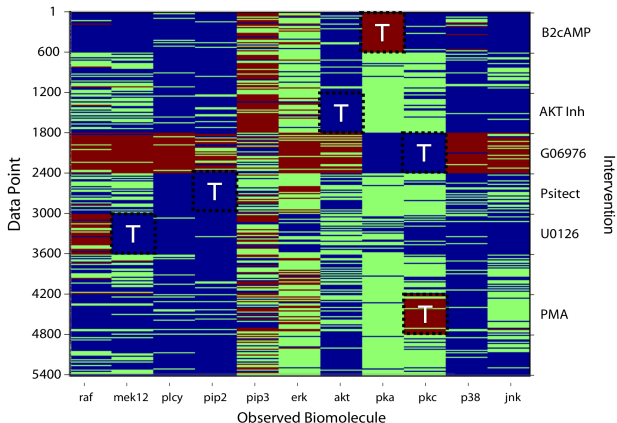
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Interventional Cell Signaling Data [Sachs et al., 2005]



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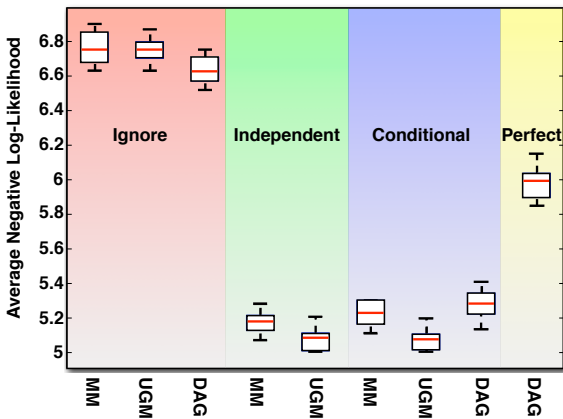
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Other Selected Extensions

Some topics not discussed:

- The methods can be extended to handle **missing data** or **hidden variables**.
- We can consider **mixtures** of sparse graphical models.
- **Stochastic approximation** methods allow MCMC for inference.
- Can be used as sub-routines in **variational Bayes** methods.
- Can be used as sub-routines in **consistent estimation** methods.
- Methods might be useful for other types of structure learning.
- Non-convex alternatives to ℓ_1 -regularization.

Summary

- ℓ_1 -Regularization is an appealing approach for graphical model structure learning.
- Prior work focuses on Gaussian and Ising graphical models.
- We considered models with group sparsity:
 - General discrete pairwise models.
 - Blockwise-sparse models.
 - Conditional models.
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